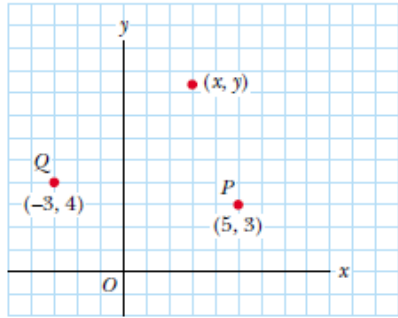


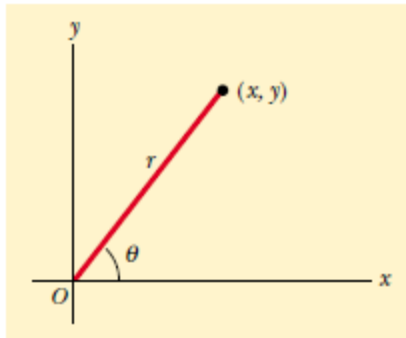
# Vectors

## Coordinate Systems

1) *Cartesian coordinates* are also called *rectangular coordinates*  $(x, y, z)$ .



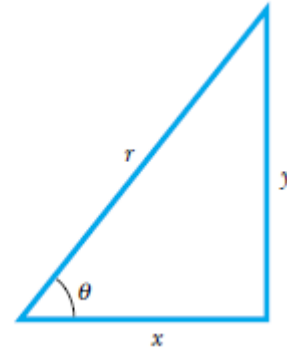
2) *Plane polar coordinates*  $(r, \theta)$



$$\sin \theta = \frac{y}{r}$$

$$\cos \theta = \frac{x}{r}$$

$$\tan \theta = \frac{y}{x}$$



$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\tan \theta = \frac{y}{x}$$

$$r = \sqrt{x^2 + y^2}$$

## Vector and Scalar Quantities

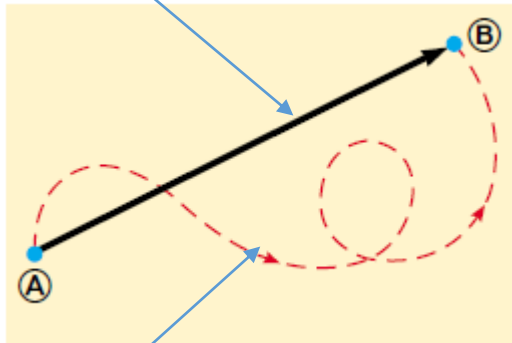
A **scalar quantity** is completely specified by a single value with an appropriate unit and has no direction.

Temperature, time, mass, distance and speed are some examples of *scalar quantities*.

A **vector quantity** is completely specified by a number and appropriate units plus a direction.

Force, displacement, velocity are some examples of *vector quantities*.

*Displacement*



*distance*

generally an arrow is written over the symbol for the vector:  $\vec{\mathbf{A}}$ .

but in most texts a bold letter represents a vector:  $\mathbf{A}$

magnitude of the vector is  $A$  or  $|\mathbf{A}|$

The magnitude of a vector is *always* a positive number and has physical units.

## Some Properties of Vectors

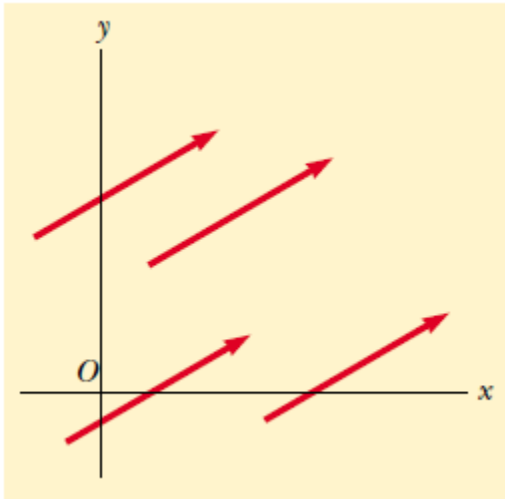
### Equality of Two Vectors

Two vectors  $A$  and  $B$  are equal if they have the same magnitude and point in the same direction.

$$\mathbf{A} = \mathbf{B}$$

only if  $A = B$  and

if  $A$  and  $B$  point in the same direction along parallel lines.

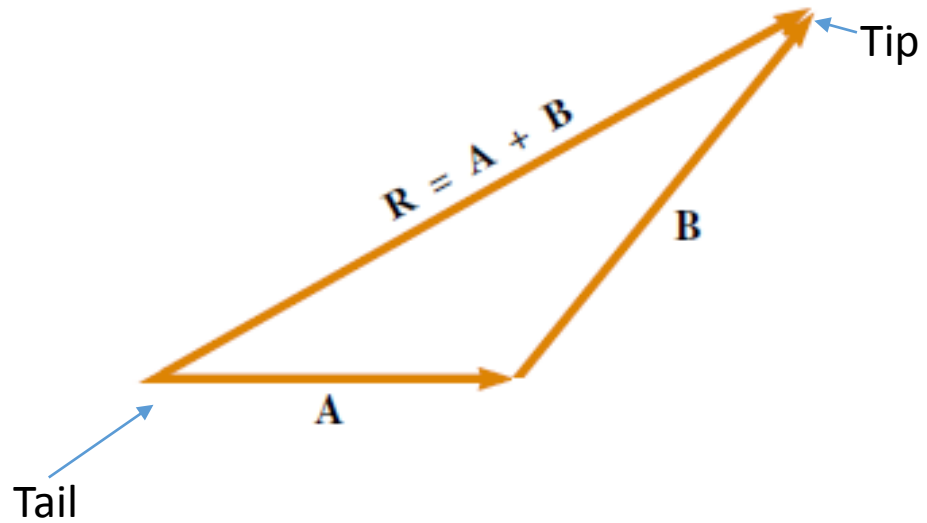


these four vectors are equal

## Adding Vectors

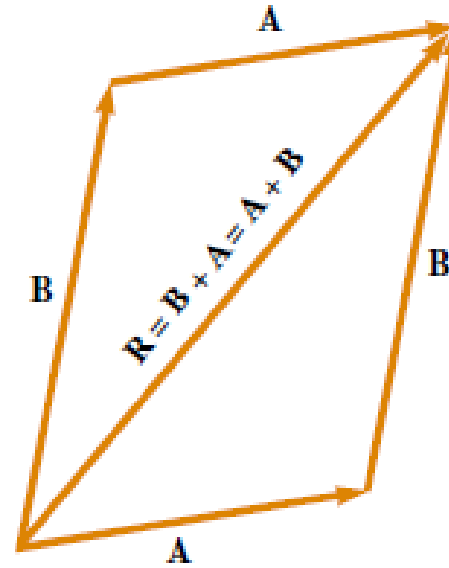
Sum of two vectors is the resultant vector

$$\mathbf{R} = \mathbf{A} + \mathbf{B}$$



commutative law of addition

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$$



associative law of addition

$$\mathbf{A} + (\mathbf{B} + \mathbf{C}) = (\mathbf{A} + \mathbf{B}) + \mathbf{C}$$

## Negative of a Vector;

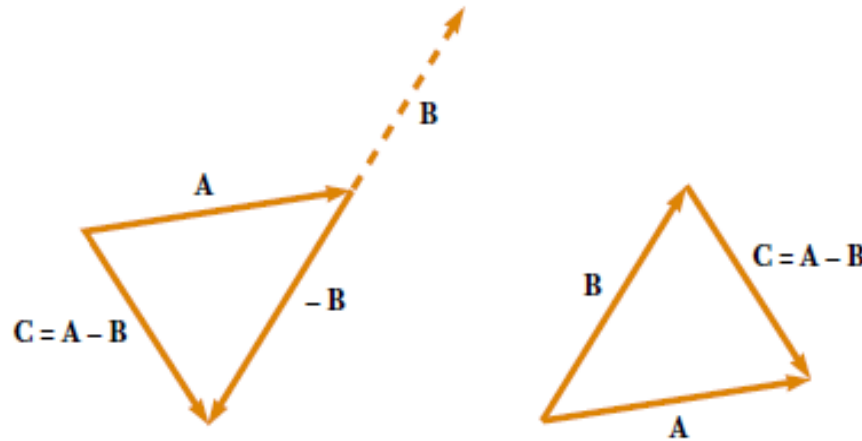
The negative of the vector  $A$  is defined as the vector that when added to  $A$  gives zero for the vector sum.

$$\mathbf{A} + (-\mathbf{A}) = \mathbf{0}$$

The vectors  $A$  and  $-A$  have the same magnitude but point in opposite directions.

## Subtracting Vectors;

$$\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B})$$



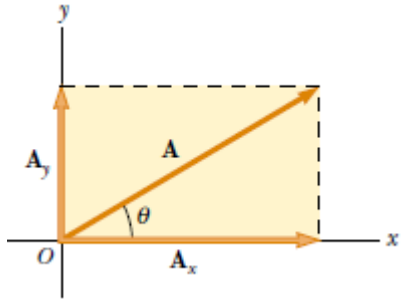
## Multiplying a Vector by a Scalar:

When vector  $\mathbf{A}$  is multiplied by a positive scalar  $m$ , then the product  $m\mathbf{A}$  is a vector with the magnitude  $mA$  and in the same direction as  $\mathbf{A}$ .

If vector  $\mathbf{A}$  is multiplied by a negative scalar  $-m$ , then the product  $-m\mathbf{A}$  is directed opposite  $\mathbf{A}$ .

For example, the vector  $3\mathbf{A}$  is three times as long as  $\mathbf{A}$  and points in the same direction as  $\mathbf{A}$ .

## Components of a Vector and Unit Vectors



$$\mathbf{A} = \hat{\mathbf{A}}_x + \mathbf{A}_y.$$

$\mathbf{A}_x$  and  $\mathbf{A}_y$  are components of vector  $\mathbf{A}$

$$A_x = A \cos \theta$$

$$A_y = A \sin \theta$$

$$A = \sqrt{A_x^2 + A_y^2}$$

$$\tan \theta = \left( \frac{A_y}{A_x} \right)$$

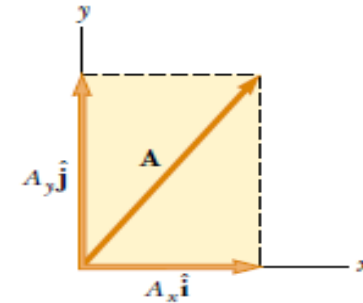
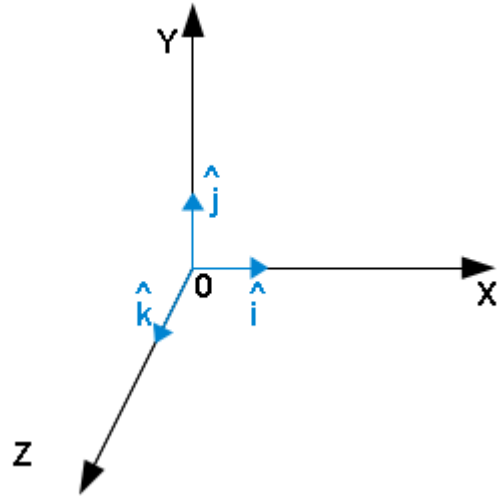
## Unit Vectors

A unit vector is a vector that has a magnitude of 1 unit.

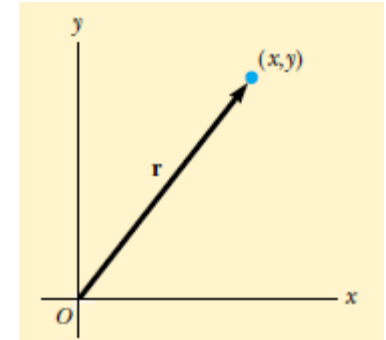
A unit vector has no dimension

A unit vector shows the direction of a vector.

$\hat{i}$ ,  $\hat{j}$ , and  $\hat{k}$  are unit vectors for x, y and z directions.



$$\mathbf{A} = A_x \hat{i} + A_y \hat{j}$$



$$\mathbf{r} = x \hat{i} + y \hat{j}$$

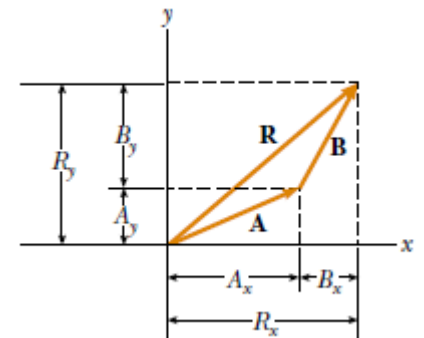
$$\mathbf{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\mathbf{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\mathbf{R} = \mathbf{A} + \mathbf{B}$$

$$\mathbf{R} = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$$

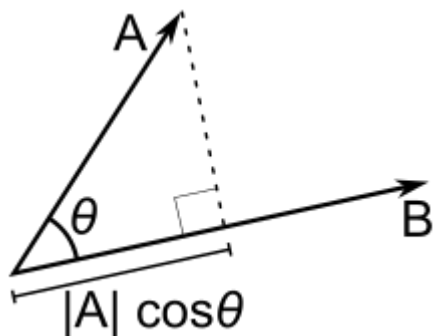
$$\mathbf{R} = (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j} + (A_z + B_z) \hat{k}$$



## The Scalar Product of Two Vectors (dot product)

$$\mathbf{A} \cdot \mathbf{B} \equiv AB \cos \theta$$

result is scalar



$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{i} \cdot \hat{k} = \hat{j} \cdot \hat{k} = 0$$

$$\mathbf{i} \cdot \mathbf{i} = (1)(1) \cos 0^\circ = 1$$

$$\mathbf{i} \cdot \mathbf{j} = (1)(1) \cos 90^\circ = 0$$

$$\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$$

$$\mathbf{A} \cdot (\mathbf{B} + \mathbf{C}) = \mathbf{A} \cdot \mathbf{B} + \mathbf{A} \cdot \mathbf{C}$$

$$\mathbf{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\mathbf{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\mathbf{A} \cdot \mathbf{A} = A_x^2 + A_y^2 + A_z^2 = A^2$$

Ex/  $\mathbf{A} = 2\hat{i} + 3\hat{j}$        $\mathbf{B} = -\hat{i} + 2\hat{j}$

a)  $\mathbf{A} \cdot \mathbf{B} = (2\hat{i} + 3\hat{j}) \cdot (-\hat{i} + 2\hat{j})$   
 $= -2\hat{i} \cdot \hat{i} + 2\hat{i} \cdot 2\hat{j} - 3\hat{j} \cdot \hat{i} + 3\hat{j} \cdot 2\hat{j}$   
 $= -2(1) + 4(0) - 3(0) + 6(1)$   
 $= -2 + 6 = 4$

b)  $A = \sqrt{A_x^2 + A_y^2} = \sqrt{(2)^2 + (3)^2} = \sqrt{13}$   
 $B = \sqrt{B_x^2 + B_y^2} = \sqrt{(-1)^2 + (2)^2} = \sqrt{5}$

$$\cos \theta = \frac{\mathbf{A} \cdot \mathbf{B}}{AB} = \frac{4}{\sqrt{13}\sqrt{5}} = \frac{4}{\sqrt{65}}$$

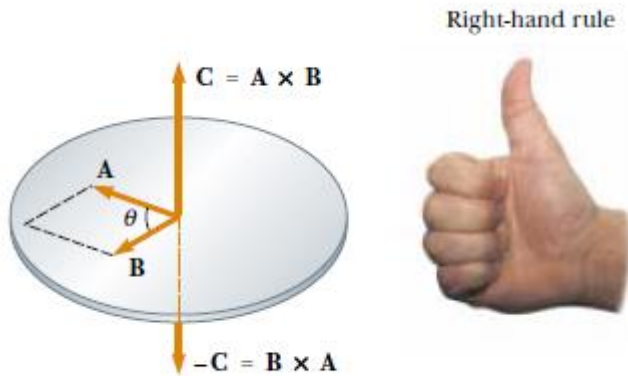
$$\theta = \cos^{-1} \frac{4}{8.06} = 60.2^\circ$$



## The Vector Product of Two Vectors (cross product)

$\mathbf{C} = \mathbf{A} \times \mathbf{B}$  result is a vector

$C \equiv AB \sin \theta$  (magnitude of the product)



$$\mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}$$

$$\mathbf{A} \times (\mathbf{B} + \mathbf{C}) = \mathbf{A} \times \mathbf{B} + \mathbf{A} \times \mathbf{C}$$

$$\mathbf{i} \times \mathbf{i} = (1)(1) \sin 0^\circ = 0$$

$$\mathbf{i} \times \mathbf{j} = (1)(1) \sin 90^\circ = \mathbf{k}$$

$$\hat{\mathbf{i}} \times \hat{\mathbf{i}} = \hat{\mathbf{j}} \times \hat{\mathbf{j}} = \hat{\mathbf{k}} \times \hat{\mathbf{k}} = 0$$

$$\hat{\mathbf{i}} \times \hat{\mathbf{j}} = -\hat{\mathbf{j}} \times \hat{\mathbf{i}} = \hat{\mathbf{k}}$$

$$\hat{\mathbf{j}} \times \hat{\mathbf{k}} = -\hat{\mathbf{k}} \times \hat{\mathbf{j}} = \hat{\mathbf{i}}$$

$$\hat{\mathbf{k}} \times \hat{\mathbf{i}} = -\hat{\mathbf{i}} \times \hat{\mathbf{k}} = \hat{\mathbf{j}}$$

determinant form

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = \begin{vmatrix} A_y & A_z \\ B_y & B_z \end{vmatrix} \hat{\mathbf{i}} - \begin{vmatrix} A_x & A_z \\ B_x & B_z \end{vmatrix} \hat{\mathbf{j}} + \begin{vmatrix} A_x & A_y \\ B_x & B_y \end{vmatrix} \hat{\mathbf{k}}$$

$$\mathbf{A} \times \mathbf{B} = (A_y B_z - A_z B_y) \hat{\mathbf{i}} - (A_x B_z - A_z B_x) \hat{\mathbf{j}} + (A_x B_y - A_y B_x) \hat{\mathbf{k}}$$

**Ex/**  $\mathbf{A} = 2\hat{\mathbf{i}} + 3\hat{\mathbf{j}}$        $\mathbf{B} = -\hat{\mathbf{i}} + 2\hat{\mathbf{j}}$ .

$$\begin{aligned}\mathbf{A} \times \mathbf{B} &= (2\hat{\mathbf{i}} + 3\hat{\mathbf{j}}) \times (-\hat{\mathbf{i}} + 2\hat{\mathbf{j}}) \\ &= 2\hat{\mathbf{i}} \times 2\hat{\mathbf{j}} + 3\hat{\mathbf{j}} \times (-\hat{\mathbf{i}}) = 4\hat{\mathbf{k}} + 3\hat{\mathbf{k}} = 7\hat{\mathbf{k}}\end{aligned}$$

$$\begin{aligned}\mathbf{B} \times \mathbf{A} &= (-\hat{\mathbf{i}} + 2\hat{\mathbf{j}}) \times (2\hat{\mathbf{i}} + 3\hat{\mathbf{j}}) \\ &= -\hat{\mathbf{i}} \times 3\hat{\mathbf{j}} + 2\hat{\mathbf{j}} \times 2\hat{\mathbf{i}} = -3\hat{\mathbf{k}} - 4\hat{\mathbf{k}} = -7\hat{\mathbf{k}}\end{aligned}$$